Robot

* Model: Techman TM 12
* Software: TM Flow

Code

Libary’s

Herkenning groente: Python

Libary’s:

OpenCV

Pyrealsense2

Numpy

HMI: HTML en flask

Libary’s:

* Flask
* Asyncio
* Techmanpy
* Time
* Copy
* Sys
* Math

Camera’s

* Intel Realsense D415
* Firmware Version: 5.14
* Resolution: 1280x720

Om de camera te kunnen calibreren gebruikten wij:

* Depth Quality tool V2.53.1